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The method of claim 165 including programming said robot to obtain a piece of material from a dispenser, and wiping said material across said portion of said first glass surface while said material is loaded with said primer composition.

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The method of claim 166 including pumping a small volume of a urethane primer to the surface of said material during said wiping such that a wet streak of said primer composition is formed on said portion of said first glass surface, and allowing said primer composition to flash off said first glass surface.

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The method of claim 164 wherein said positioning includes acquiring said attachment member with said robot and locating said attachment member on said portion of said first glass surface within about 30 seconds after said adhesive is deposited on said at least one of said attachment member mounting surface and said first glass surface.

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The method of claim 168 including holding said attachment member against said substrate with said robot for a time period less than or equal to about 30 seconds after said positioning of said attachment member.

REMARKS

Claims 1-130, as originally filed in the grandparent application, have been canceled herein and new claims 131-169 have been added. Examination on the basis of claims 131-169 is respectfully requested.

In addition, the specification has been amended to add a Cross Reference to the prior applications from which this application is continued, and to add the patent number of the application referenced on page 19.

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New claims 131-169 are fully supported by the application as originally filed.

No new matter has been added.

Accordingly, examination on the basis of new claims 131-169 and a Notice of Allowance is respectfully requested.

Respectfully submitted,

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Date 12/17/98

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